

# LIDAR

Roger Hirschman  
GIS Coordinator  
USDA Natural Resources  
Conservation Service

# **What is LIDAR?**

- Remotely Sensed Elevation Data**

# **Why Would You Want LIDAR?**

- High Accuracy (15cm ~ 6in)**
- High Spatial Resolution (1-2m)**
- Can be Collected in Vegetated Areas**
- Cost Effective**

# LIDAR (Light Detection And Ranging)

## Laser:

Pulsing thousands of times per second

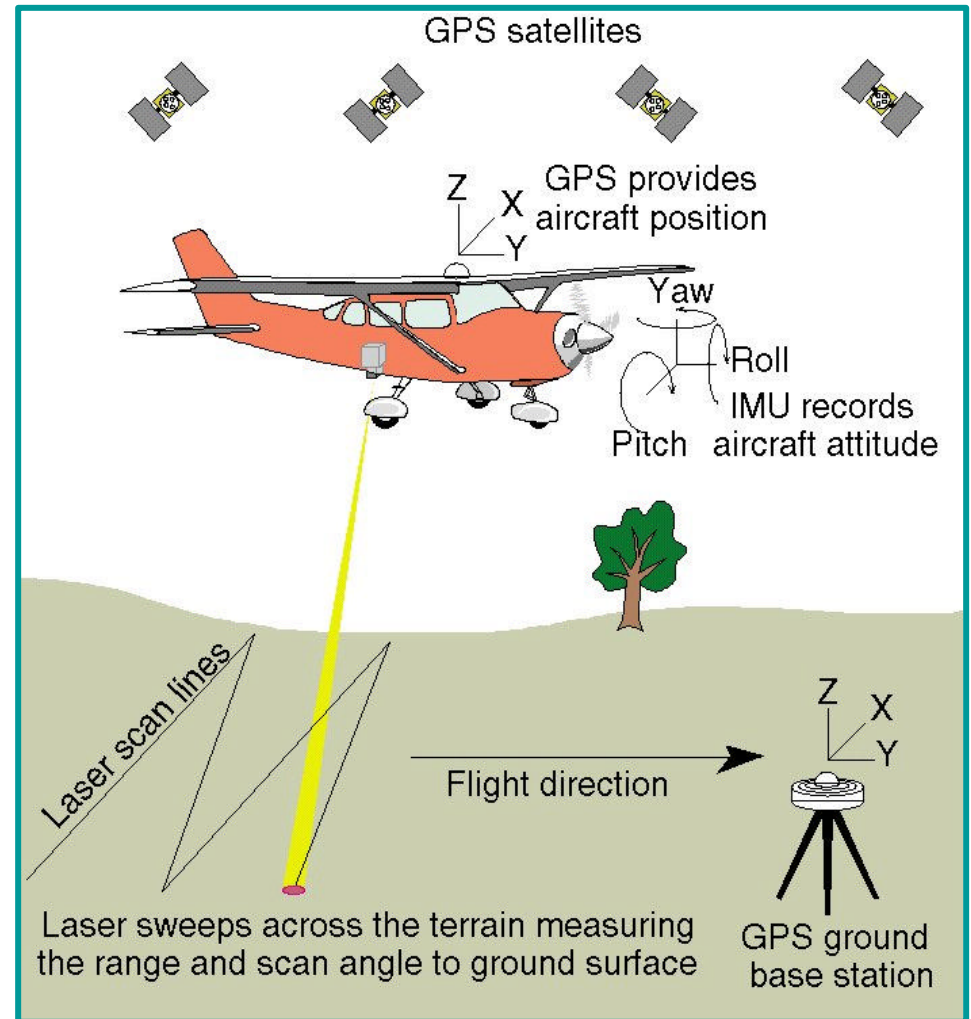
## GPS:

Provides the exact location on the aircraft

## IMU:

An Inertial Measurement Unit used to remove the effects of Roll, Pitch and Yaw

All three data streams (laser ranges, IMU information, and GPS positions) are merged and processed to generate a series of topographic points.



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# LIDAR System

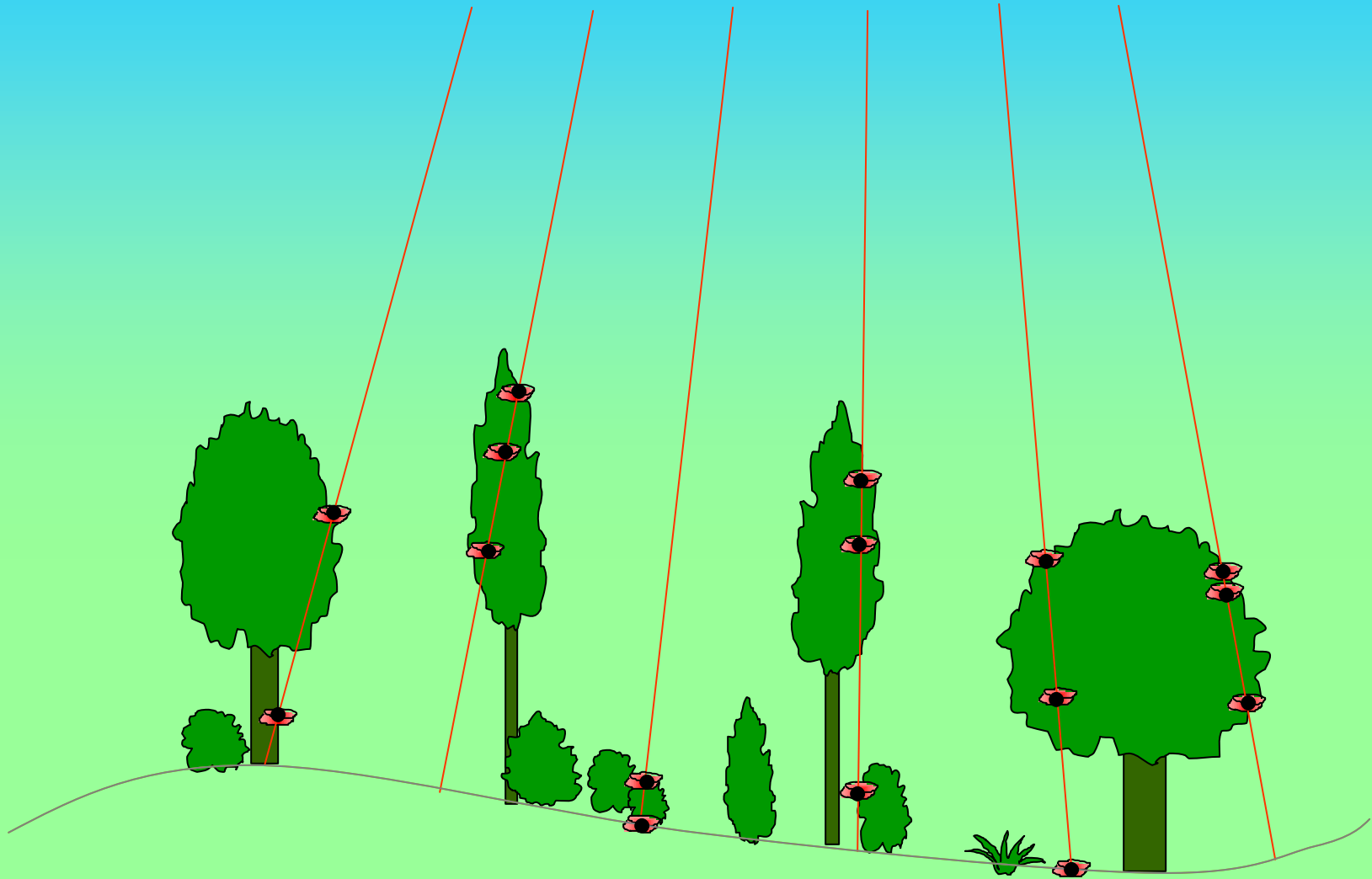
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- Laser pulse rate: up to 25,000 per sec.
- Laser scan angle: variable up to  $\pm 20^\circ$ , depending on scan rate.
- Operating altitude: 410-2000 m above ground level (AGL)..

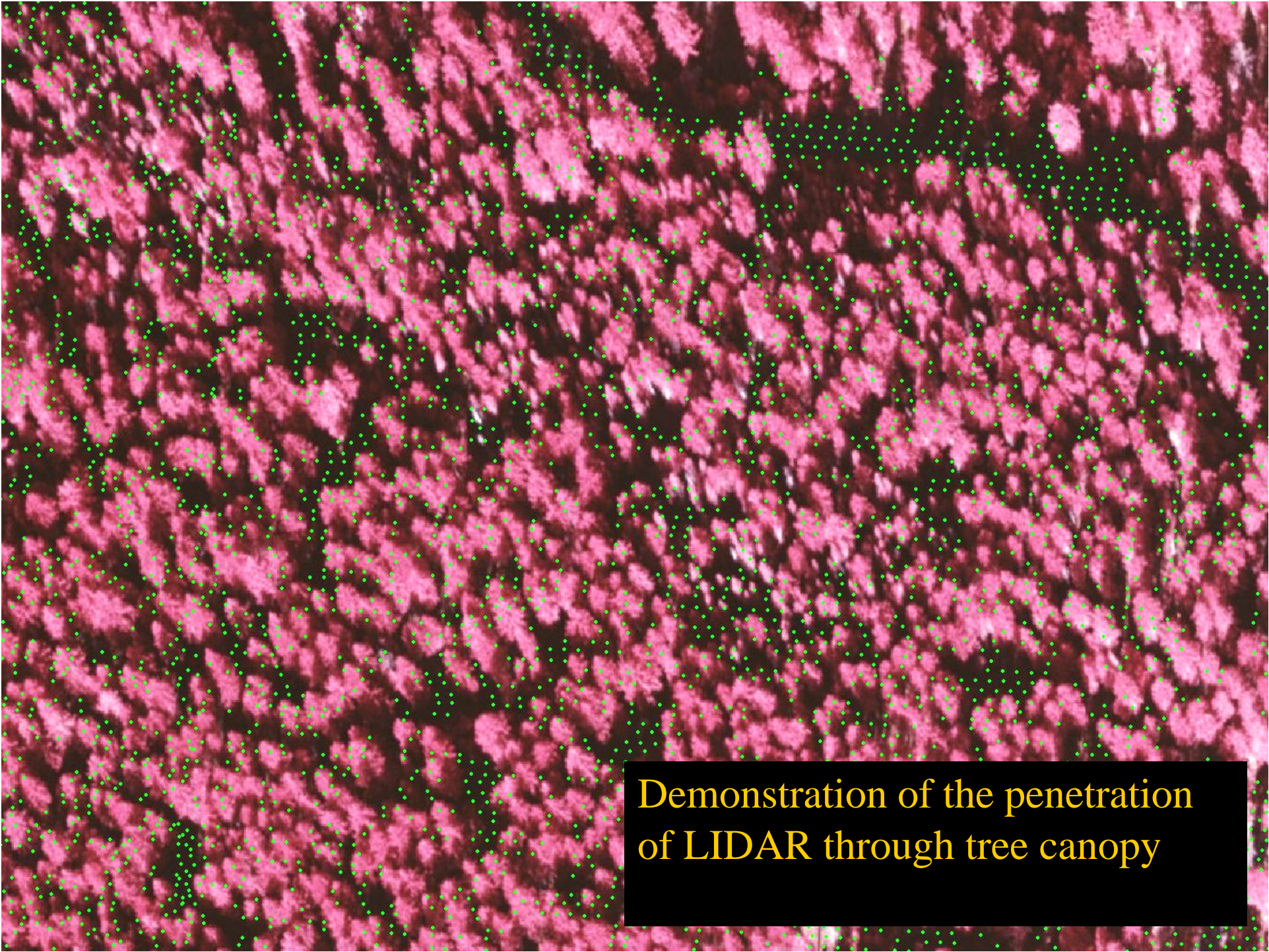


ALTM system  
A. Laser and IMU,  
B. Computer/equipment rack  
C. Ashtech Z-12 GPS receiver.

# Multiple Return





An aerial photograph of a dense forest canopy, rendered in a monochromatic green and black color scheme. The image is overlaid with a dense distribution of small, bright green dots, which represent LIDAR point cloud data. These dots are scattered across the entire forest area, with a higher concentration in the upper right quadrant, illustrating the penetration of LIDAR through the tree canopy.

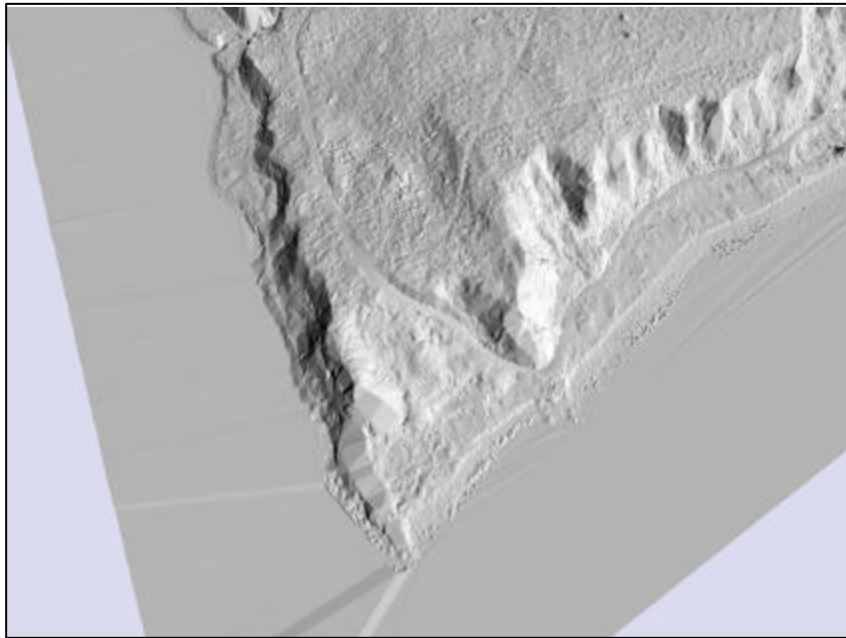
Demonstration of the penetration  
of LIDAR through tree canopy



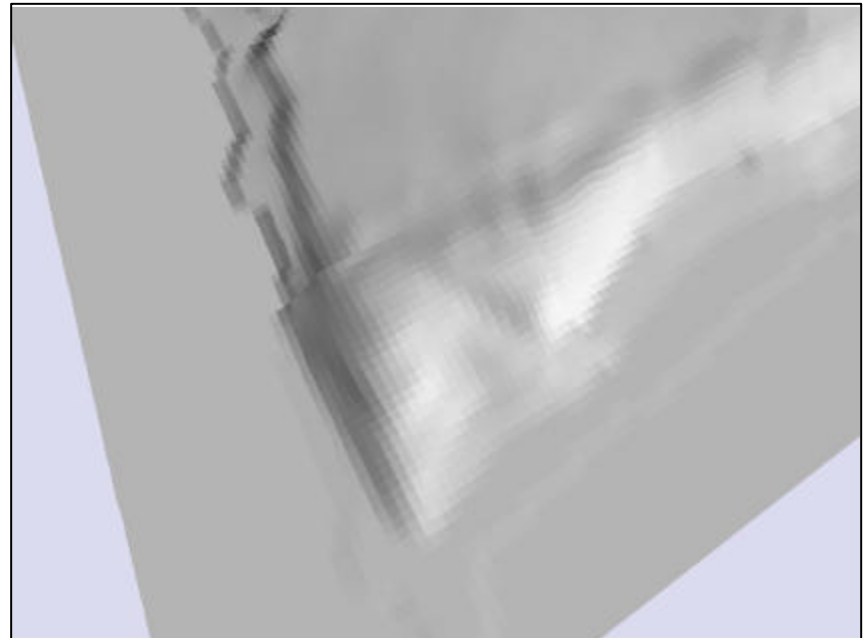
# Comparison of Terrain Models LIDAR and 10 Meter DEM



LIDAR

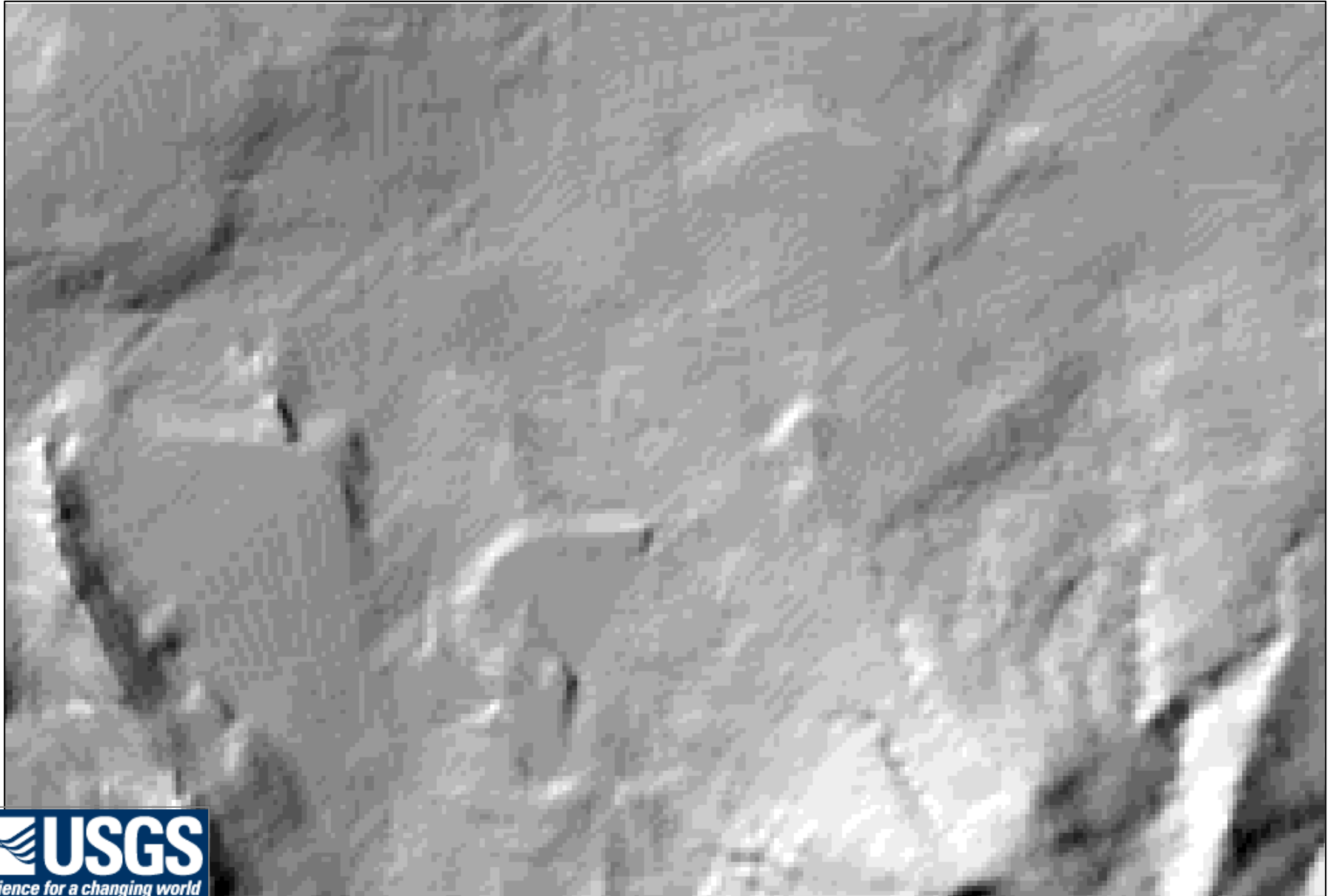


10 Meter DEM



Images from **Puget Sound LIDAR Consortium**

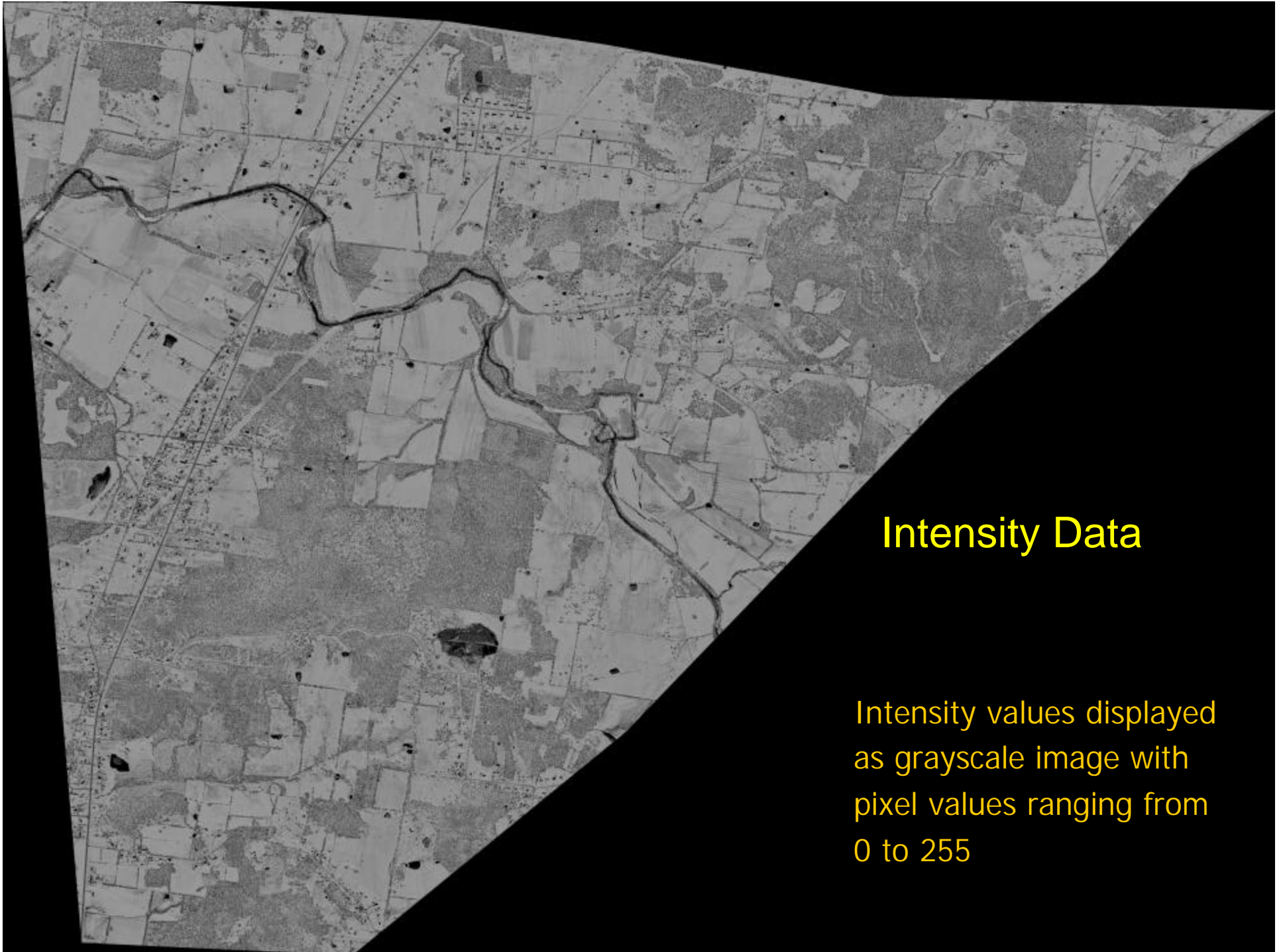
# USGS 10-meter DEM





# LIDAR 2-meter DEM





## Intensity Data

Intensity values displayed  
as grayscale image with  
pixel values ranging from  
0 to 255

# LiDAR Data

**Data Collected in a Single  
Day's Flight**

**150-200 million elevation  
points**

**1 Gbyte per Hour of  
LiDAR, GPS, and IMU  
data.**

# LIDAR & Photo Collection

LIDAR and photo acquisition should always be performed as close to the same date as absolutely possible.

Features may appear absent in the LIDAR when compared to the photos or vice versa.

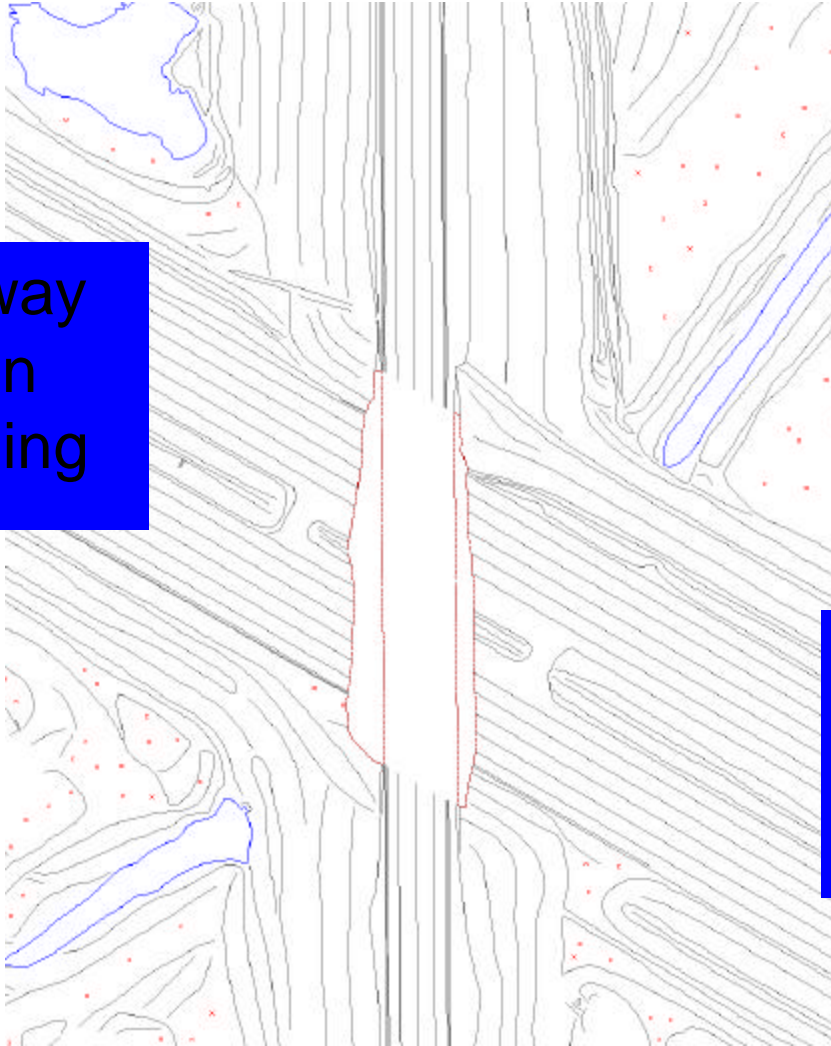
Water features fluctuate in capacity very rapidly.



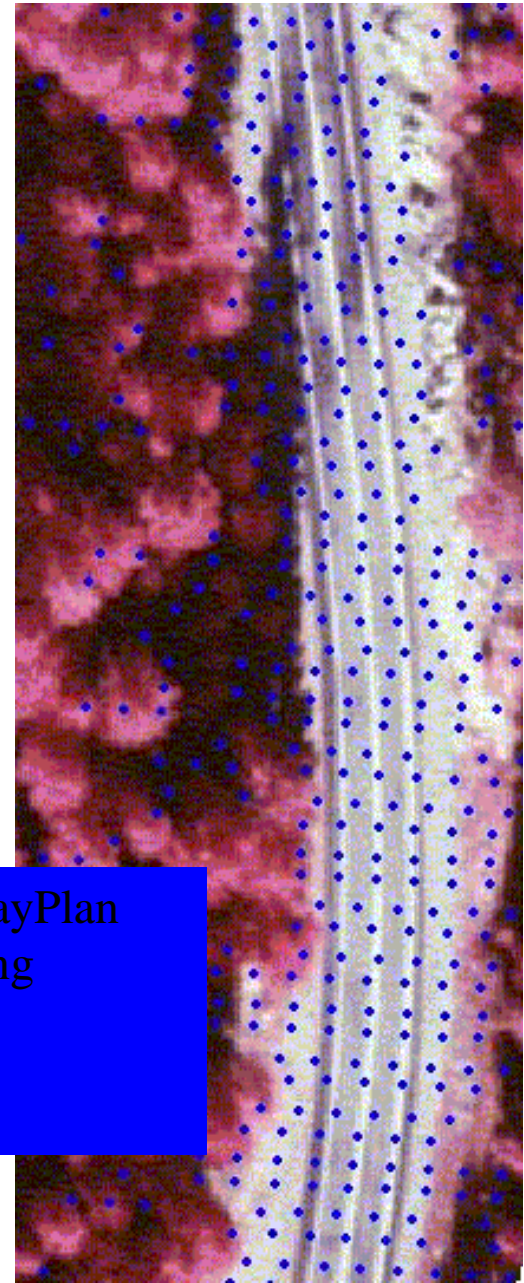
# MAPPING APPLICATIONS

# Transportation Applications

- Highway Design Mapping



Highway Plan Mapping

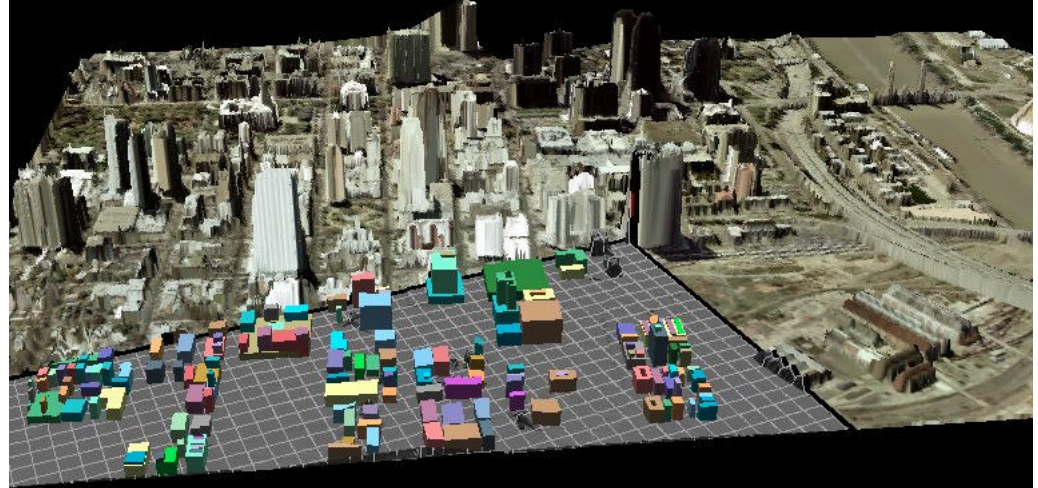
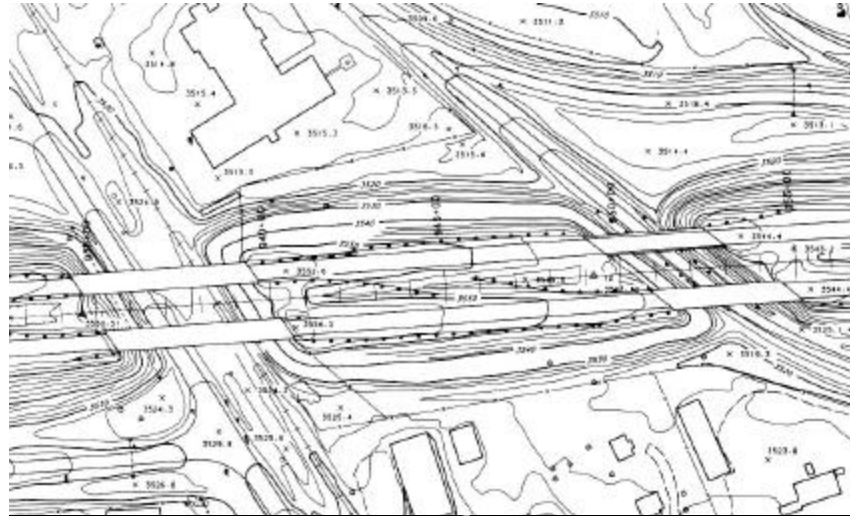


# Color Shaded Elevation Model / Image Comparison

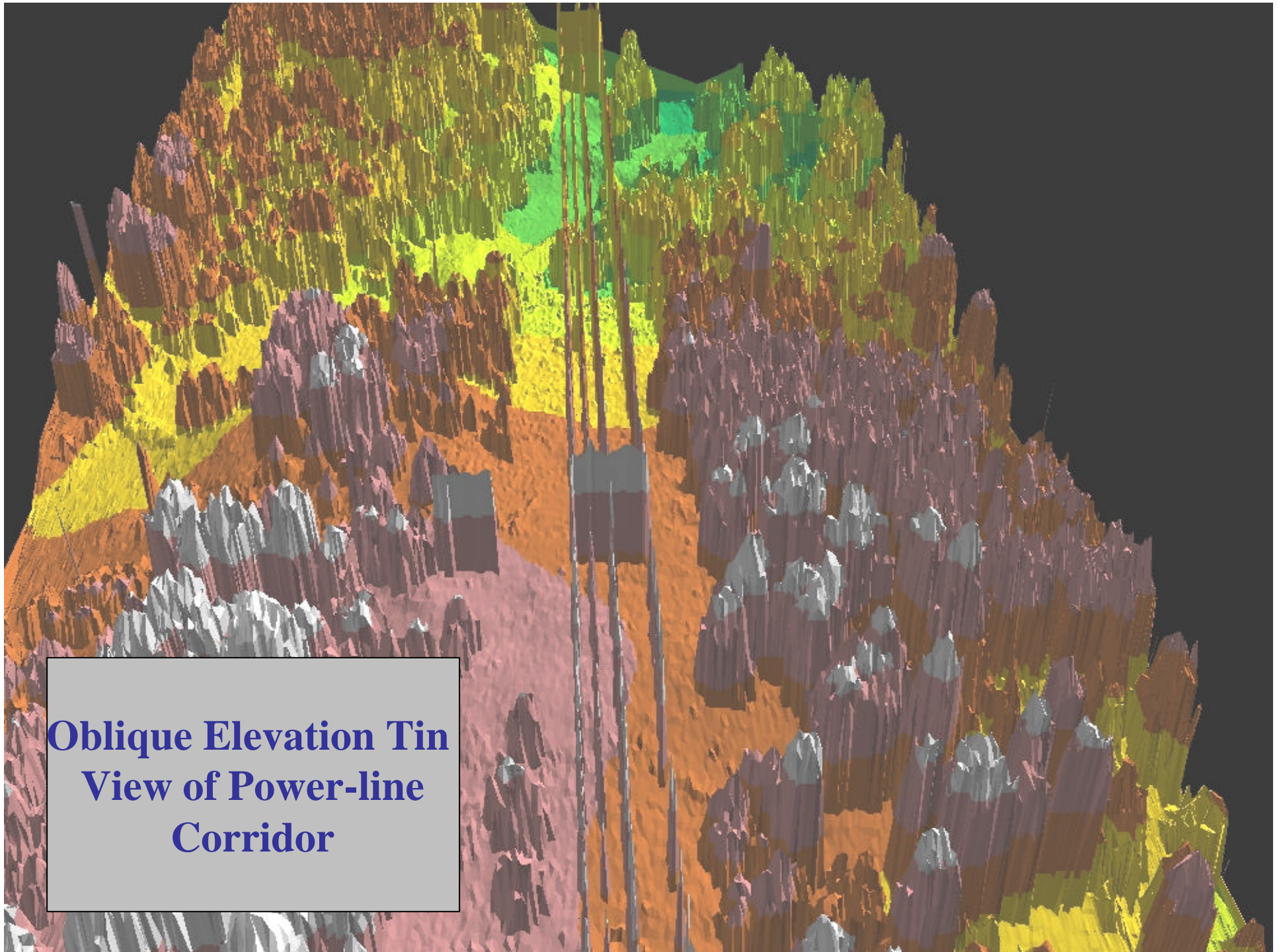


# Urban Applications

- Contours
- 3D Visuals
- Classification
  - Structures
  - Vegetation
  - Bare Earth
  - Water
- Orthophoto
- DEM



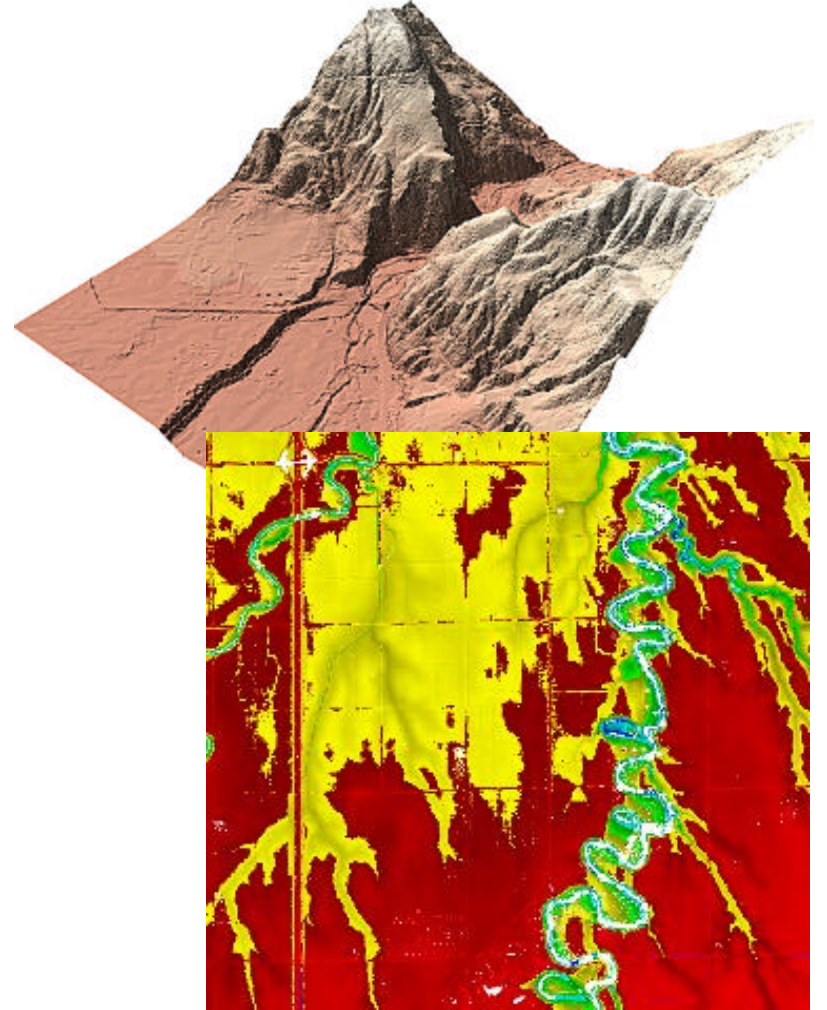




**Oblique Elevation Tin  
View of Power-line  
Corridor**

# Watersheds and Floodplains

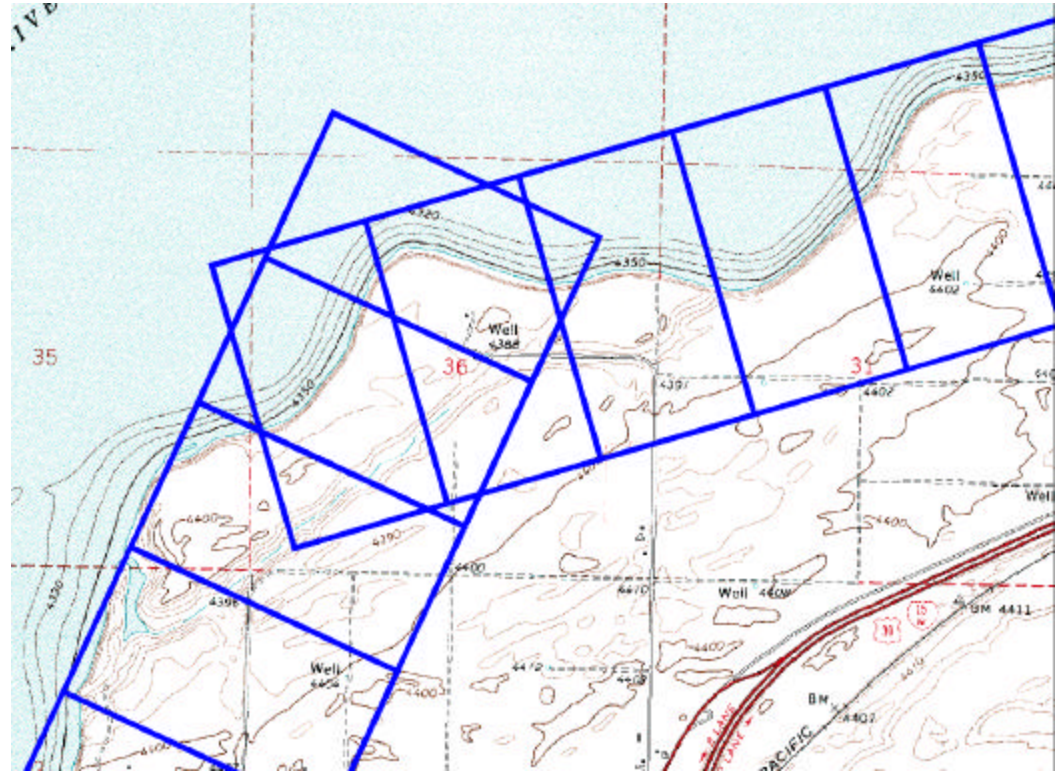
- Economic Solution for Large Area Elevation Models
- Supports 2' contour interval maps
- Meets FEMA specifications with the addition of breaklines





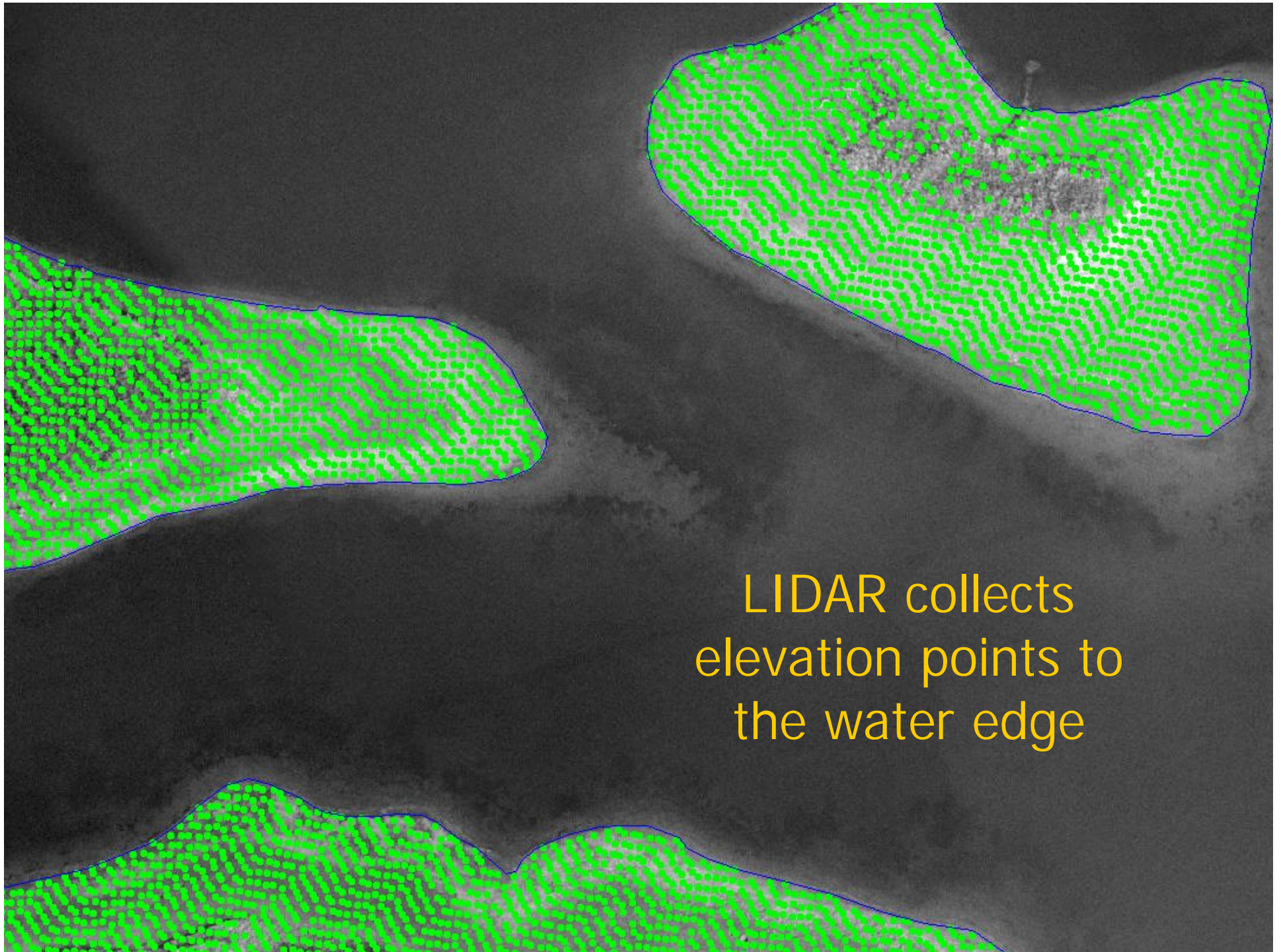
# Reservoirs

Challenge to  
conventional  
mapping



- Irregular shoreline
- Unpredictable water levels
- Inability to perform photo control across stereo models of water

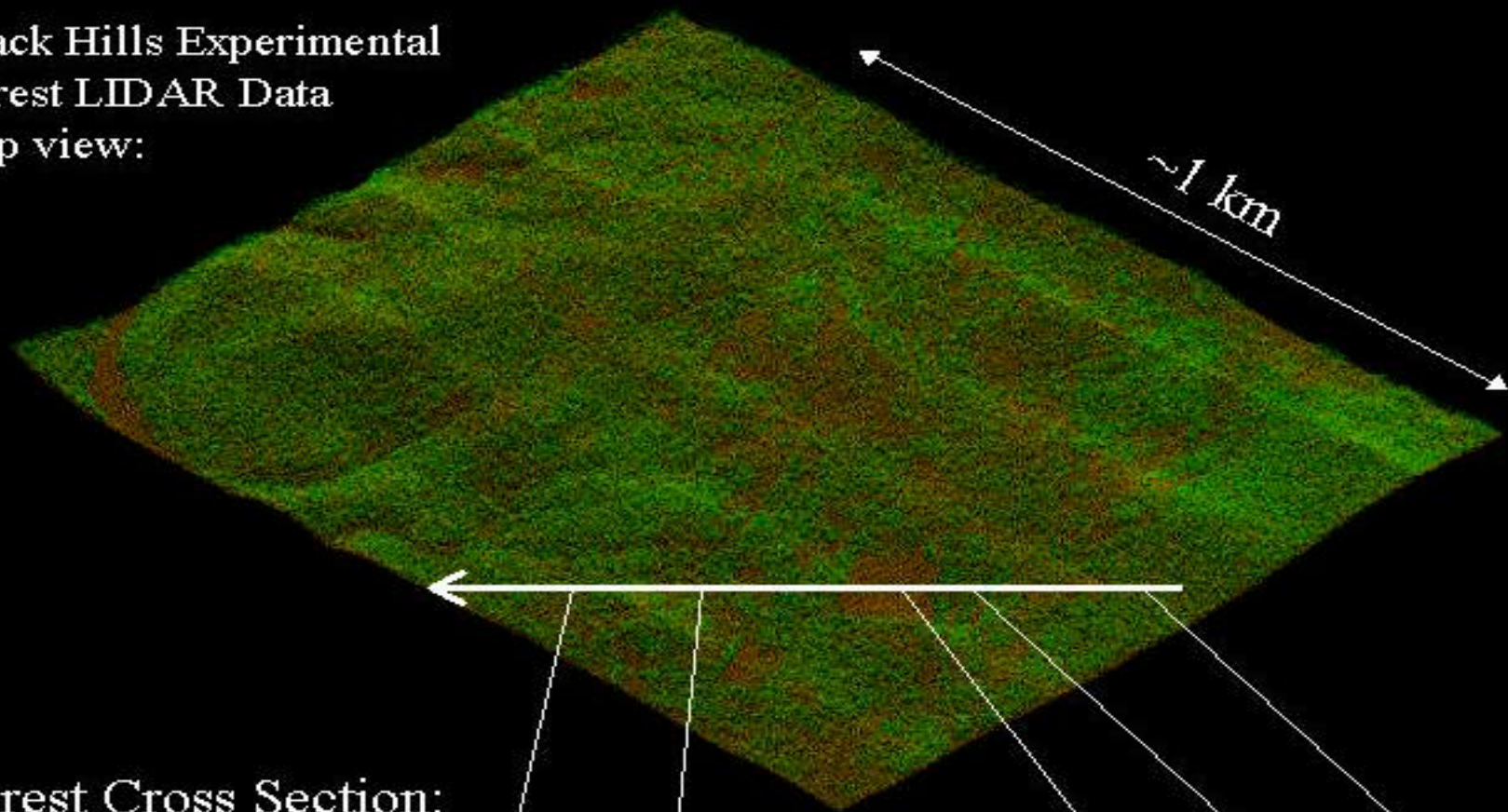




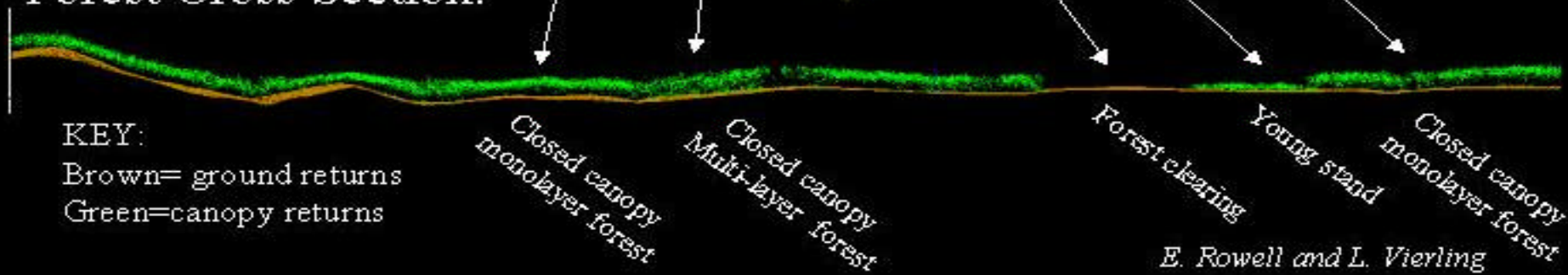
LIDAR collects  
elevation points to  
the water edge



Black Hills Experimental  
Forest LIDAR Data  
map view:



Forest Cross Section:



*E. Rowell and L. Vierling*

# LIDAR Advantages

- Rapid collection of dense topographic data over large areas
- Multiple return capability
- Inexpensive topographic mapping over large areas when compared to traditional photogrammetry
- Much longer annual collection period
- Ability to collect data at night and in shadowed areas

# LIDAR Disadvantages

- Smaller projects may be more expensive than traditional photogrammetry due to mobilization costs
- Fog, haze, and extremely high humidity will cause noise pollution in the resulting datasets
- Extreme fields of view tend to produce vibration noise within the datasets
- Limitations on post-spacing

# Conclusions:

## **-Highly Accurate Remotely Sensed Elevation Data**

~15-cm or 6-inches Vertical Accuracy

## **-Becoming Very Cost Effective**

## **-Wide Range of Uses**

- Flood Forecasting
- Reservoir Planning
- Changes in Topography
- Vegetative Analysis
- Wetland Mapping
- Urban Modeling
- Watershed Modeling
- Geologic Fault Mapping
- Viewshed Analysis

## **-Collect Multiple Datasets on the Same Flight**

- LIDAR
- Hyperspectral Imagery
- Digital Photography



# Cooperative Project

## USDA – NRCS

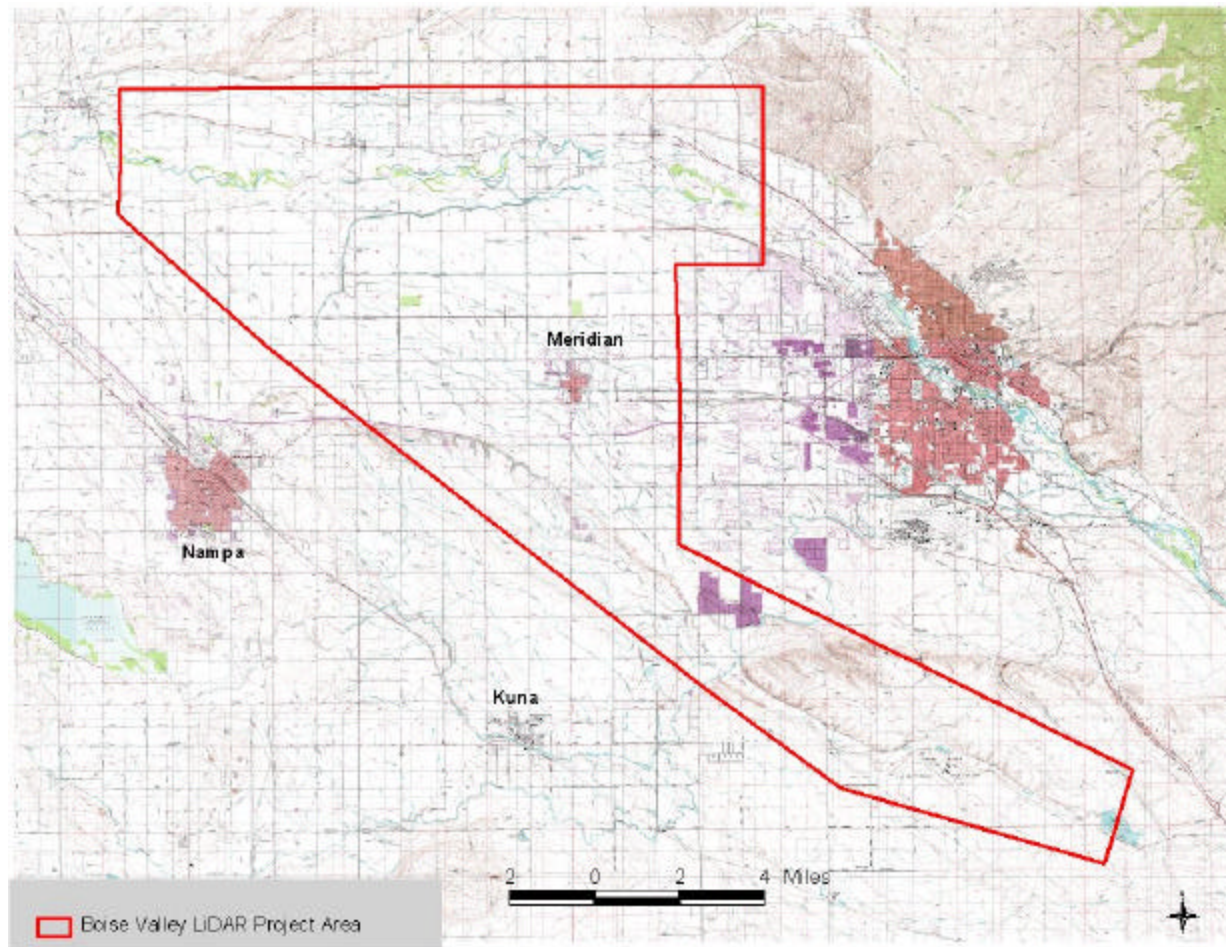
## USDI – BOR

Need for accurate, detailed DEM

NRCS - Update soil survey (low relief  
landscape & soil types)

BOR – Study effect of urbanization on  
drains once used for Ag runoff

# Study Area



# Deliverables

- Raw Data
- 1<sup>st</sup> Return DEM
- Bare Earth DEM
- Intensity Image

# Specifications

- Leaf Off
- No Water in Drains or Canals
- November 1, 2003 – March 1, 2004
- $< 5\%$  Snow Cover



# FY 2004

- NRCS requested additional funding for Boise Valley LiDAR
- BOR may have additional funding
- Looking for additional partners
- Anywhere in state

Contact: Roger Hirschman

[roger.hirschman@id.usda.gov](mailto:roger.hirschman@id.usda.gov)

208 378-5785 x1